

## Kater's Reversible Pendulum 1018466

### Instruction manual

09/16 TL/DU



- 1 Pendulum
- 2 Stand
- 3 Floor cover

### 1. Safety instructions

When carefully assembled and properly used, safety of experimenting with the reversible pendulum can be guaranteed. There is, however, a possible risk of injury or damage to the pendulum if care is not taken.

- Read this instruction manual all the way through and observe it in full.
- Set up the stand on solid, level ground and fasten the assembly screws tightly.
- Fasten the securing screw for the movable pendulum bob tightly so that the bob can not move unchecked.
- Use the adjustment screws in the base plate of the stand to align the bearing plate in such a way that the bearing axes of the pendulum bob can be even.
- Always handle the pendulum with both hands when setting it up or adjusting it.
- Carefully suspend the pendulum from the bearing plate and check that the bearing axes are in the correct positions.
- Do not subject the pendulum to excessive pushes and do not deflect it by more than 10 cm at the bottom end.

## 2. Components

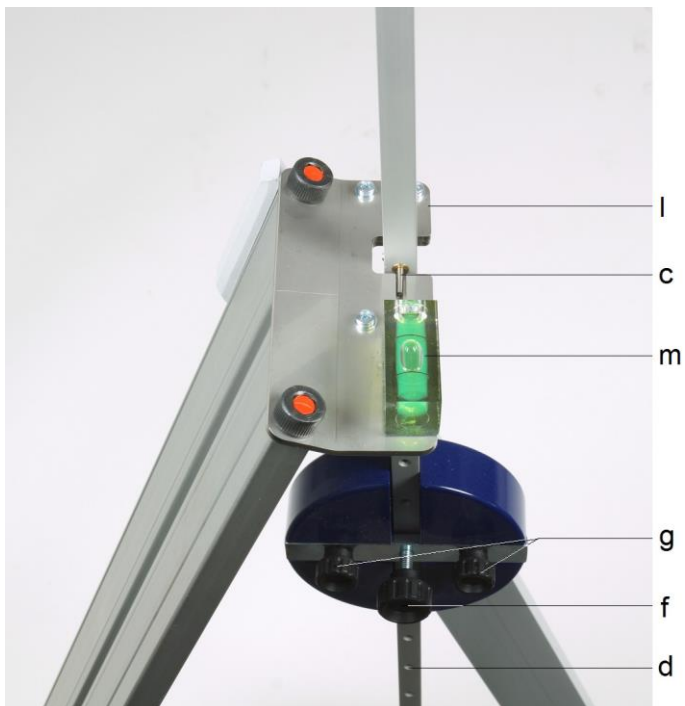


### Pendulum

- a Fixed pendulum bob
- b Pendulum rod
- c Bearing fulcrum
- d Latch-in positions
- e Movable pendulum bob
- f Securing screw
- g Assembly screws

### Stand

- h Stand board
- i Positioning screws
- j Stand rod
- k Stand board
- l Bearing plate
- m Spirit level
- n Floor cover



### 3. Description

The reversible pendulum is a physical pendulum with two bearing fulcra plus one fixed and one movable pendulum bob. It oscillates in its stand either with a period of oscillation  $T_1$  about the first bearing fulcrum or period  $T_2$  about the second fulcrum. By shifting the movable pendulum bob it is possible to adjust both these periods until they are equal. The pendulum then has a reduced length equal to the distance  $d$  between the bearing axes and the following equation applies:

$$T_1 = T_2 = 2\pi \cdot \sqrt{\frac{d}{g}}, \quad g: \text{acceleration due to gravity}$$

When it is moved, the movable weight latches into place every 2.5 cm. For finer movements the bob can be turned by 180° about the vertical and mounted that way round.

### 4. Technical data

Period of calibrated pendulum (calculated assuming $g = 9.81 \text{ m/s}^2$ ):	1794 ms
Overall dimensions:	80x125x30cm <sup>3</sup>
Overall weight:	6.3 kg approx.
Length of pendulum rod:	120 cm
Separation between bearing fulcra:	80 cm
Fixed pendulum bob:	1.4 kg approx.
Movable pendulum bob:	1.0 kg approx.
Pendulum deflection	max. 10 cm

### 5. Set-up

#### 5.1 Choice of set-up location

If the floor on which the equipment is set is springy, then the oscillation energy is transferred to the whole stand and measurement errors can then arise.

- Only set up and use the reversible pendulum on solid, level ground.

On smooth, slippery or sensitive surfaces:

- Put a mat under the base plate and the strut of the stand.

#### 5.2 Assembly of stand

- Undo the screw (see Fig. 1), fold out the stand rod.

- Secure it in its operating position with a moderate degree of torque.

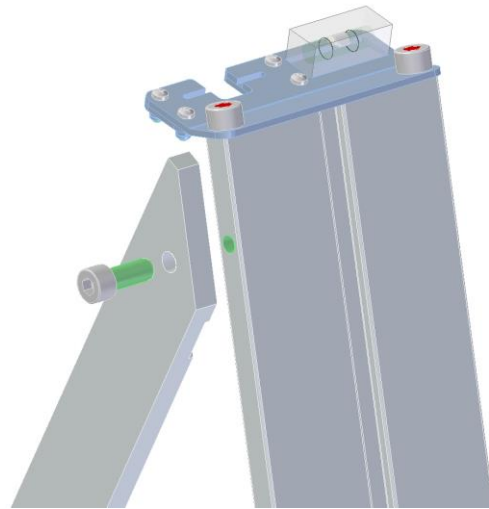


Fig. 1: Attachment of stand rod to stand board

#### 5.3 Vertical positioning of the pendulum rod

- Grip the pendulum with both hands and carefully suspend it from the bearing plate (see Fig. 2).
- The vertical positioning of the pendulum rod should be adjusted using the positioning screws in such a way that the bubble of the spirit level is centered (see Fig. 3).

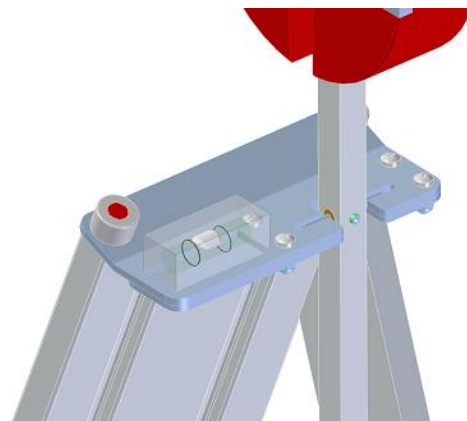


Fig. 2: Bearing plate with pendulum rod suspended



Fig. 3: Setting position with the help of the spirit level

## 6. Operation

### 6.1 Moving the pendulum rod

- Use gentle pressure to move the pendulum in the direction of the arrow with several pushes at the position marked until the deflection is about 5 cm.

*Note: Larger deflections can lead to non-negligible measurement errors.*

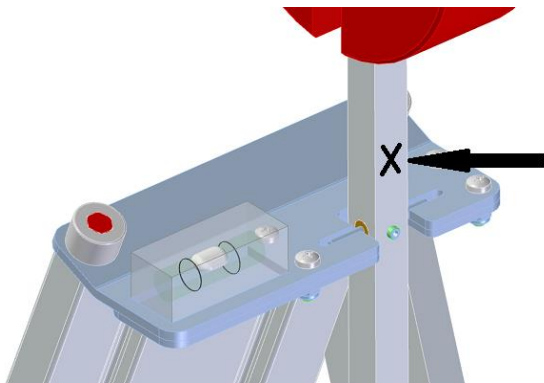


Fig. 4: Moving the pendulum rod

### 6.2 Reversing the pendulum position

- Use both hands to lift the pendulum out of the bearing plate and turn it around.
- Carefully suspend the pendulum from the bearing plate by its other fulcrum. Then carry on as in step 6.1.

### 6.3 Period of oscillation depending on the position of the movable pendulum bob



Fig. 5: Experiment set-up with light barrier and digital counter

*Additionally required:*

1 Light barrier	1000563
1 Digital counter (@230 V)	1001033
or	
1 Digital counter (@115 V)	1001032

- Set up the light barrier under the pendulum rod while it is stationary and connect the barrier to the digital counter (see Fig. 5).
- Suspend the pendulum rod from the bearing plate in such a way that both the fixed bob (red) and the movable bob (blue) are below their corresponding fulcra.
- Attach the movable bob in the wedge-shaped groove nearest to the fixed bob, i.e. the lowest one. This position will subsequently be referred to as measuring point 1 (even when the pendulum rod is suspended above the other fulcrum).
- Measure the period of oscillation and make a note of it.
- Keep moving the movable bob from one groove to the next and secure it (measuring points 2 – 13). In each case, measure the period of oscillation and make a note of it.
- Now suspend the pendulum rod from the bearing plate in such a way that the fixed pendulum bob (red) is above the relevant fulcrum and the movable bob (blue) is below its bearing.
- Secure the movable pendulum bob in the wedge-shaped groove nearest to the fixed bob, i.e. the highest one. This position will subsequently be referred to as measuring point 1 (see above).
- Measure the period of oscillation and make a note of it.
- Keep moving the movable bob from one groove to the next and secure it (measuring points 2 – 13). In each case, measure the period of oscillation and make a note of it.
- Plot a graph of the periods of oscillation determined in both sets of measurements as a function of the numbers  $n$  of the measurements (see Fig. 6).

### 6.4 Determination of acceleration due to gravity

The periods of oscillation  $T_1$  and  $T_2$  are identical at the two points where the curves intersect and at these points they are equal to the period of oscillation  $T_0$  of the calibrated pendulum, i.e.  $T_0 = T_1 = T_2$ .

From the period duration  $T_0$  measured in step 6.3 for a calibrated reversible pendulum and a distance  $l = 0.8$  m between the two fulcra, corresponding to the shortened pendulum length, it is possible to determine the acceleration due to earth's gravity:

$$g = 4 \cdot \pi^2 \cdot \frac{l}{T_0^2}.$$

*Note: To adjust the pendulum so that both periods of oscillation are exactly the same, it may be necessary to turn the pendulum bob by 180° about the vertical and mount it on the pendulum rod that way round.*

## 7. Storage, cleaning, and disposal

- Keep the apparatus in a clean, dry, dust-free place.
- Do not use aggressive cleaning agents or solvents to clean the apparatus.
- In order to clean the equipment, use a soft, damp cloth.
- The packaging should be disposed of at local recycling centres
- If the equipment itself is to be disposed of, it must not be included with normal household waste. Local regulations are to be obeyed.

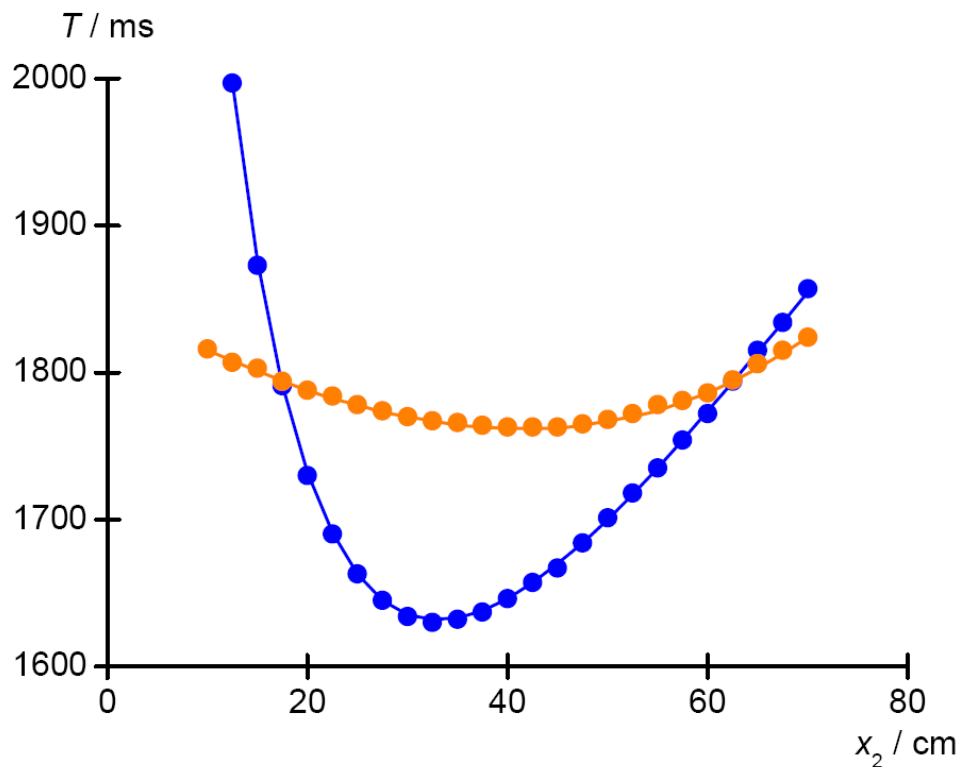
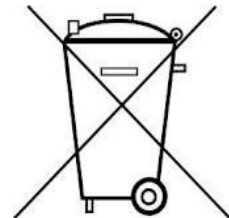


Fig. 6: Period of oscillation  $T$  as a function of measuring point number  $n$ . Red circles: Both pendulum bobs below fulcrum. Black squares: Fixed pendulum bob above fulcrum, movable bob below

